#### I. Homework to be handed in before 10:06 a.m., Wednesday, January 19

Let *S* be the set of all vectors (x, y, z) in  $\mathbf{R}^3$  such that x + y + z = 0.

a)Show that *S* is a subspace of  $\mathbb{R}^3$ . b)Find a basis for *S*.

# II. Homework to be handed in before 10:06 a.m., Wednesday, January 26

Explain carefully what is wrong with **Theorem 3.10** (page 107 of the Apostol textbook).

#### III. Homework to be handed in before 10:06 a.m., Wednesday, February 3

In the real linear space C(0, ) with inner product (x, y) = x(t)y(t)dt, let

$$x_n(t) = \sqrt{\frac{2}{2}} \sin nt.$$

a)Prove that  $S_N = \{x_1, x_2, ..., x_N\}$  is an orthonormal set. b)Find the element  $y_N$  of the span of  $S_N$  nearest to f(t) = 1. c)Find  $\|y_N - f\|^2$ .

# IV. Homework to be handed in before 10:06 a.m., Wednesday, February 9

Let  $\mathbf{T} : \mathbf{R}^4$   $\mathbf{R}^4$  be defined by  $\mathbf{T}(x_1, x_2, x_3, x_4) = (x_1 + x_2 + x_3 + x_4, 3x_1 + 2x_2 + 2x_4, 7x_1 + 4x_2 - 2x_3 + 4x_4, 2x_1 + x_2 - x_3 + x_4)$ a)Find a basis for the null space of  $\mathbf{T}$ .

b)Find a basis for the range of **T**.

## V. Homework to be handed in before 10:06 a.m., Wednesday, February 16

For each  $\mathbf{x} = \mathbf{R}^2$ , let  $\mathbf{T} = (\mathbf{x})$  be the vector resulting from rotating  $\mathbf{x}$  through an angle in a counterclockwise direction about the origin.

a)Find the matrix representation with respect to the usual basis  $\{i, j\}$  of the linear function  $\mathbf{T} : \mathbf{R}^2 = \mathbf{R}^2$  so defined.

b)Find the vector that results from rotating  $\mathbf{x} = (14, -23)$  60 degrees about the origin (counterclockwise).

c)Find the matrix representation of the composition  $\mathbf{T} \mathbf{T}$ .

d)Observe that  $\mathbf{T} = \mathbf{T}_{+}$ , and deduce a familiar trigonometric identity.

#### VI. Homework to be handed in before 10:06 a.m., Wednesday, February 23

Let

<i>A</i> =	1	2	3	5	
			3		
	2	2	5	6.	
	1	3	4	5	

a)Find the determinant d(A) and prove you have the correct answer. (Telling me what **Matlab** or *Maple* or *Mathematica*, *etc.*, says is **not** a proof.

b)If A has an inverse, find its determinant. Otherwise, explain carefully how you know A is not invertible. (Here also do not simply take the word of some computer program.)

Let

$$\mathbf{A} = \begin{array}{c} 5 & 4 \\ 4 & 5 \end{array}$$

a)Find a diagonal matrix similar to A.

b)Use the result of part a) to find a square root of **A**. In other words, , find a matrix **R** so that  $\mathbf{R}^2 = \mathbf{A}$ .

#### VIII. Homework to be handed in before 10:06 a.m., Wednesday, April 5

**1.** Exercise #7, page 159

**2.** Exercise #13, page 226

## IX. Homework to be handed in before 10:06 a.m., Wednesday, April 19

Let S be the surface with equation  $x^2 + 2yz = 0$ , where (x, y, z) are coordinates with respect to the standard basis for  $\mathbf{R}^3$ . Find an orthonormal basis  $E = \{u_1, u_2, u_3\}$  for  $\mathbf{R}^3$  so that the coordinates  $(\tilde{x}, \tilde{y}, \tilde{z})$  of the points of S with respect to E satisfy an equation in which there are no "cross product" terms—that is, the equation involves only  $\tilde{x}^2$ ,  $\tilde{y}^2$ , and  $\tilde{z}^2$ . Identify and sketch the surface.

# X. Homework to be handed in before 10:06 a.m., Wednesday, April 26

1. Suppose the square matrix 
$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & & & \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}$$
 has the property that  
 $|a_{ii}| > \prod_{\substack{j=1 \\ j=i}}^{n} |a_{ij}|$  for each  $i = 1, 2, ..., n$ .

Explain how you know A is invertible.

2. Suppose A and B are n x n matrices, and suppose A is invertible and | | < 1 for every eigenvalue of  $A^{-1}B$ . Explain how you know the matrix A + B is invertible.